



Benchmarking few-shot learning techniques for steel surface defect detection

[Rayen Ghali](#)¹, Zhor Benhafid¹, Sid-Ahmed Selouani¹

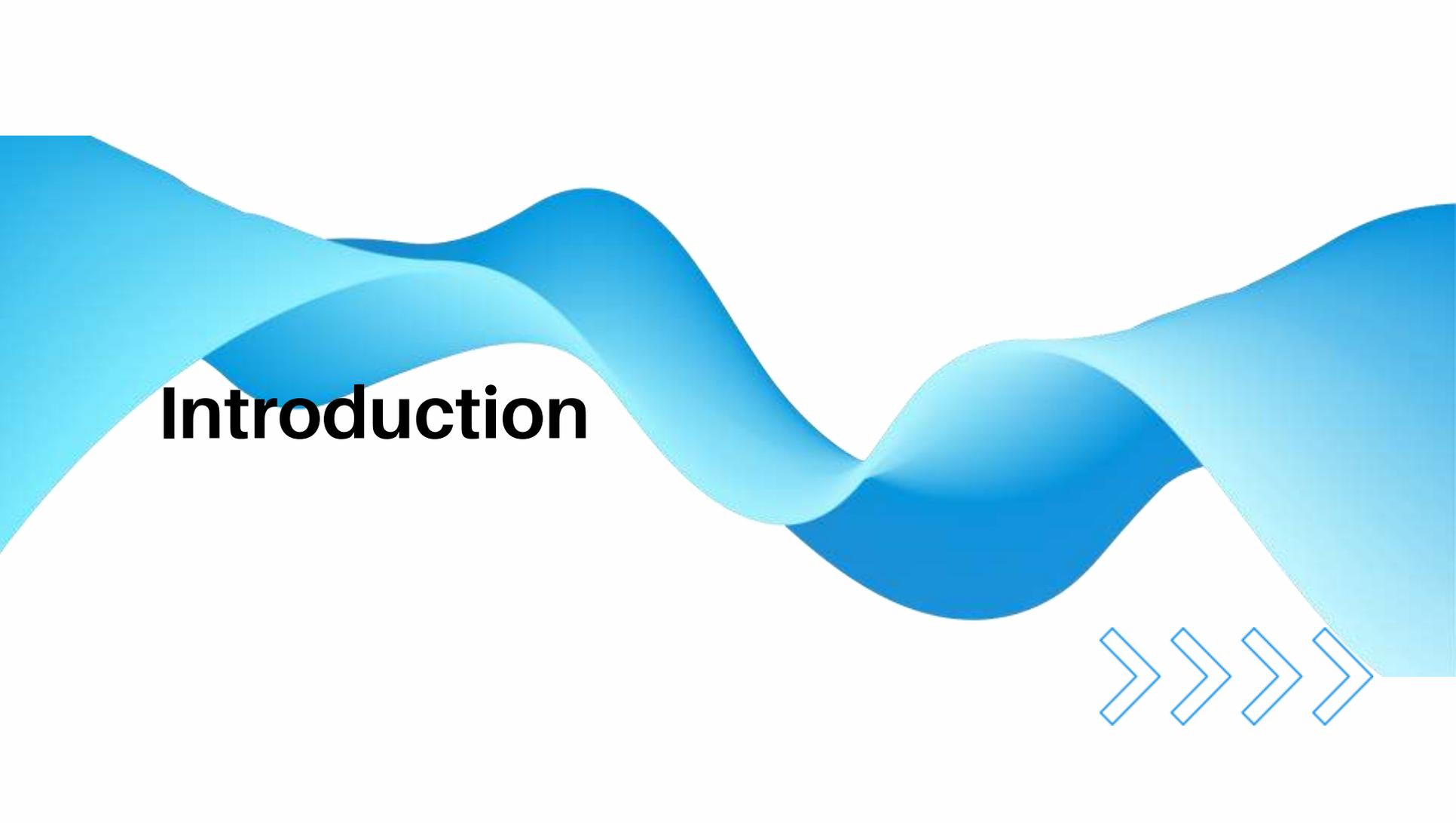
¹Laboratoire de Recherche en Interaction Humain-Système (LARIHS), Université de Moncton, Canada



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OUTLINE

- Introduction
- Background
- Methodology
- Results & Discussion
- Conclusion

The background of the slide features a series of overlapping, wavy blue shapes that create a sense of movement and depth. The colors range from a light, airy blue to a deeper, more saturated blue. The waves flow from the left side of the frame towards the right.

Introduction



Industrial vision applications



Pick & Place



Assembly

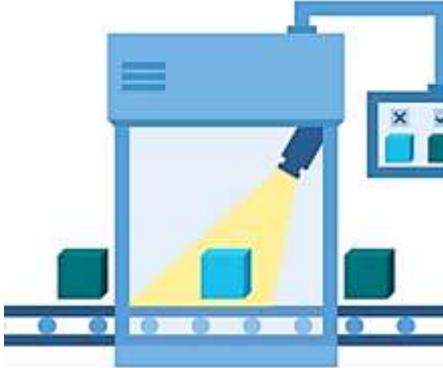


Quality assurance



Machine tending

Smart manufacturing



Automated quality inspection

Integrating AI into quality inspection



Consistent product quality



Reduced labor costs



Predictive maintenance

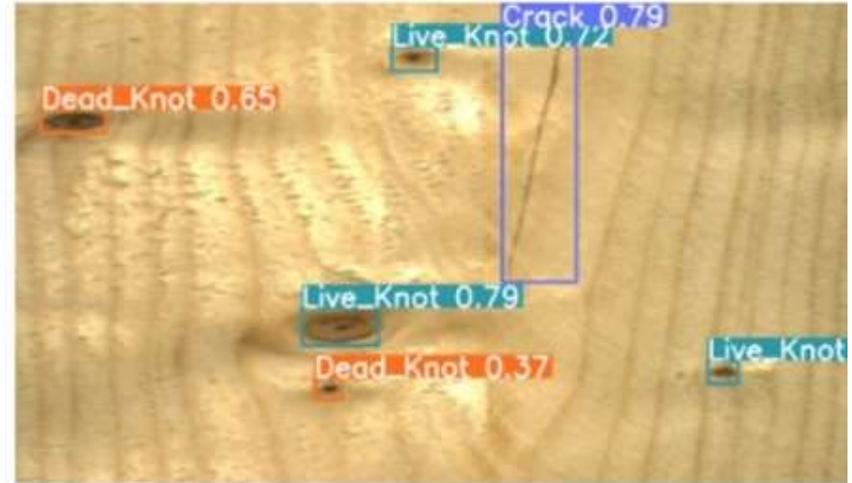
Industrial vision & automatic defect detection by AI



Input Image



Classification and localization



Challenges



- Textural complexity of defects and diverse morphological features.
- Variability of the context, resulting from changes in lighting conditions, viewpoints, and occlusions.
- Training deep learning models requires large annotated datasets, but scarce defects—appearing infrequently or unpredictably—make it more challenging.
- Manual annotation is expensive and time-consuming.
- Requirements for real-time inference.

Few-Shot Learning (FSL)



- Learn from very few examples (typically 1-10 per class).
- Mimics human ability to generalize from limited examples.
- Reduces annotation effort and deployment time.
- Enables rapid adaptation to new defect types.

Paper contributions



- Introduced SSL-YOLO, a method combining contrastive self-supervised learning with the YOLOv8 detector.
- Categorized FSL approaches by their pre-training data source and fine-tuning scope.
- Validated our approach by benchmarking its performance on steel surface defect detection across the defined FSL scenarios.

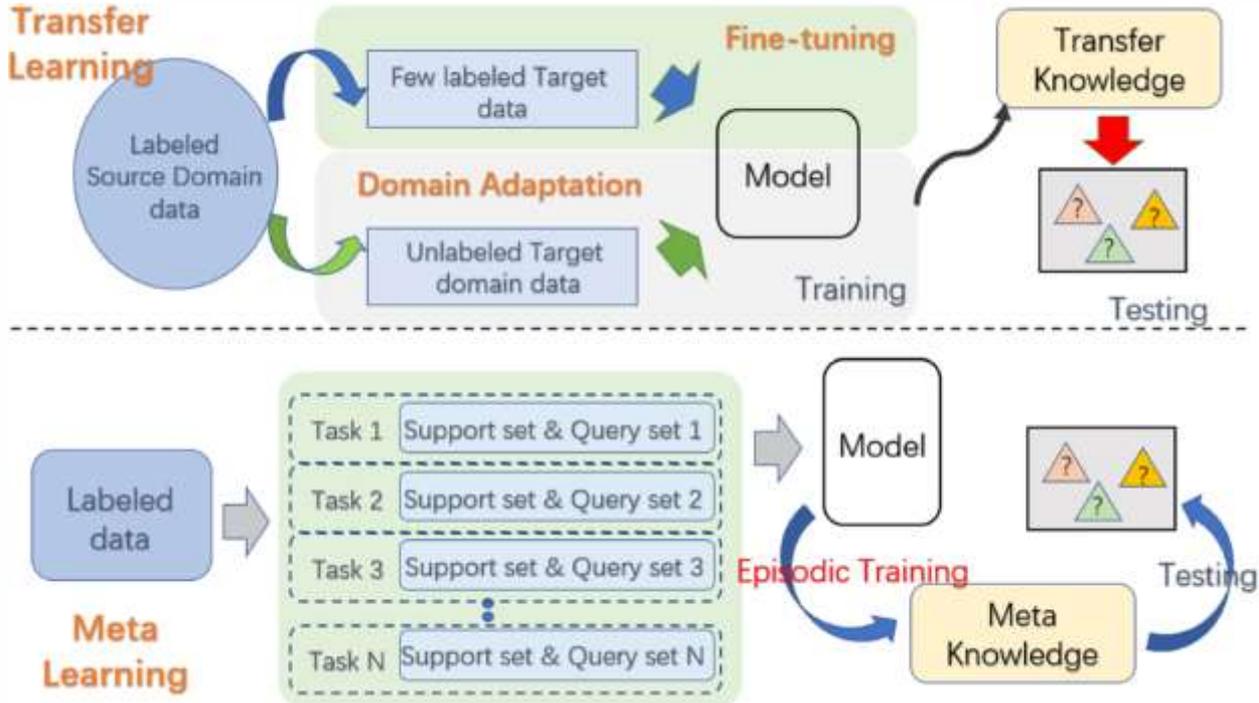
A decorative graphic consisting of several overlapping, wavy, ribbon-like shapes in various shades of blue, ranging from light cyan to a deep, vibrant blue. The shapes flow from the left side of the frame towards the right, creating a sense of movement and depth.

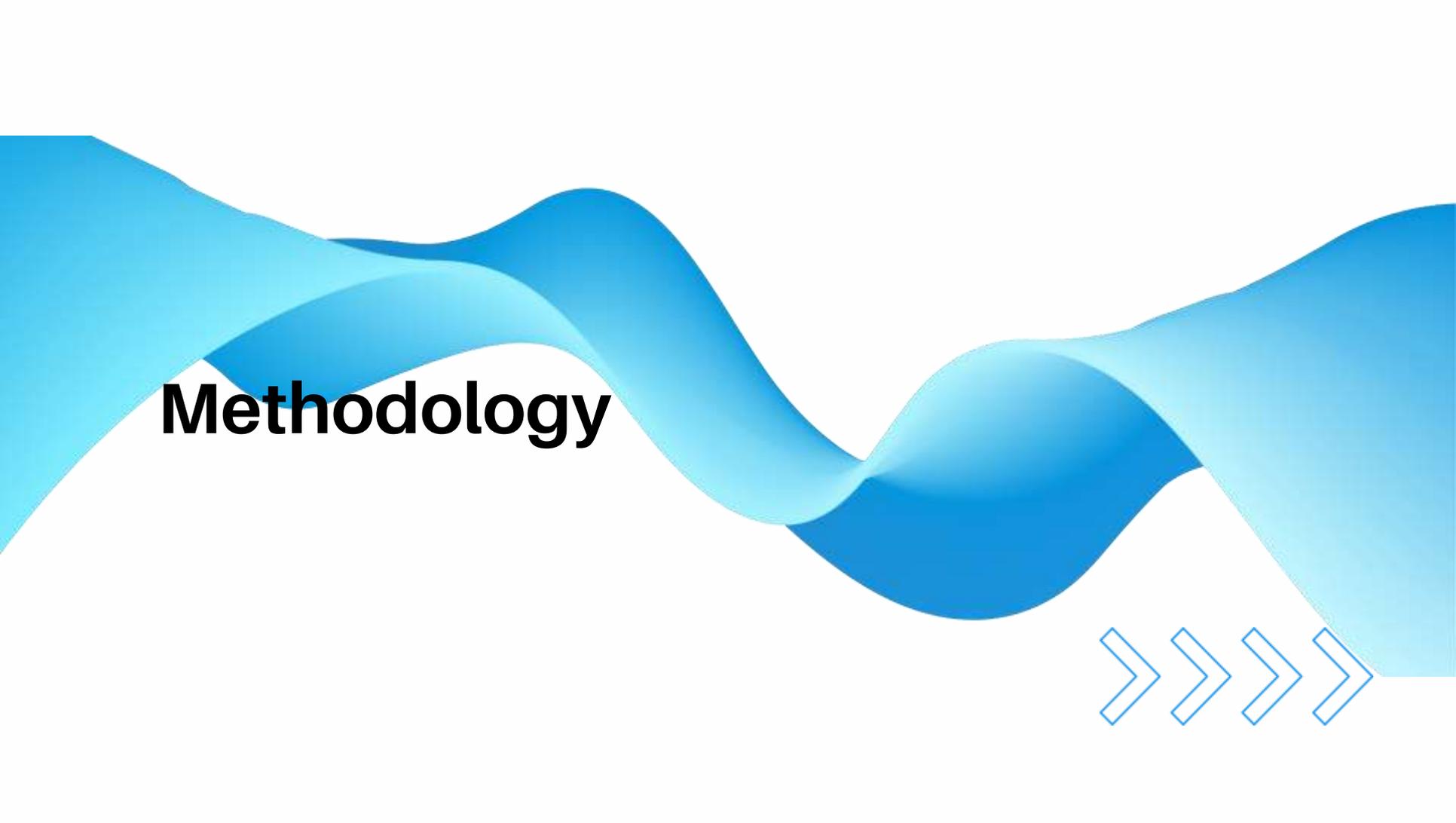
Background



Few-Shot Learning methods:

Transfer Learning vs Meta-Learning

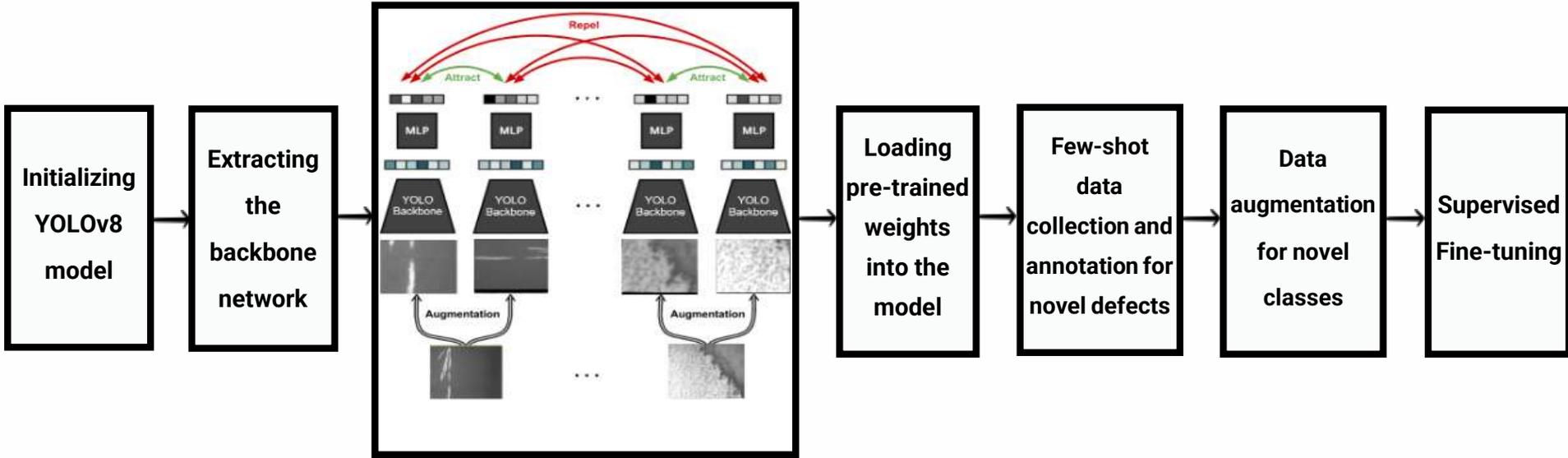


The background of the slide features a series of overlapping, wavy bands in various shades of blue, ranging from light sky blue to a deeper cerulean. These bands flow horizontally across the frame, creating a sense of movement and depth. The word "Methodology" is positioned in the lower-left quadrant, partially overlapping the blue waves. In the bottom right corner, there are four light blue chevron symbols pointing to the right, arranged in a slightly staggered horizontal line.

Methodology



SSL-YOLO Overview : Pipeline



SSL-YOLO Overview :

Applied augmentations



Original Image



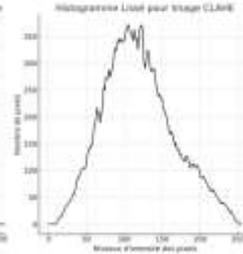
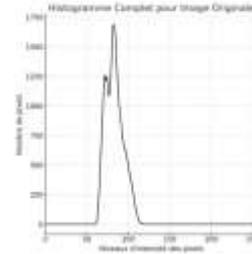
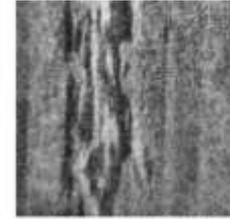
Brightness and Contrast ColorJitter



Random Translation



CLAHE (Contrast Limited Adaptive histogram equalization)



Gaussian Blur



Random Rotation



Random Resized Crop

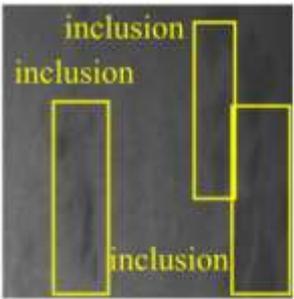


Dataset for steel surface defects (NEU-DET)

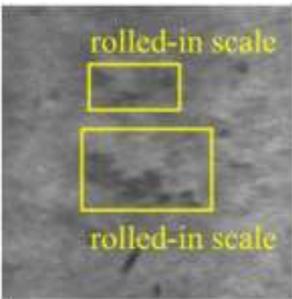


- NEU-DET - Northeastern University Surface Defect Database
- 1,800 grayscale images (200×200 pixels)
- 6 defect categories, 300 images each
- Standard split: 240 training, 60 testing per class

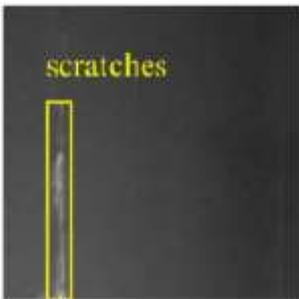
Dataset for steel surface defects (NEU-DET)



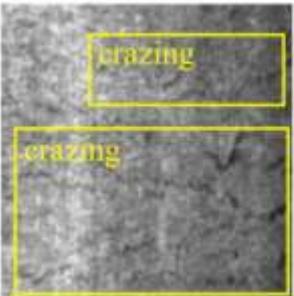
Inclusions



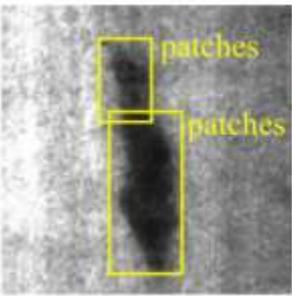
Rolled in scale



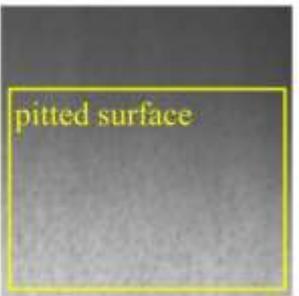
Scratches



Crazing



Patches



Pitted surface

Experimental setup :

Evaluation split

- For robust and reproduceable results, we follow the public **Few-Shot NEU-DET (FS-ND)** [2] evaluation protocol, performing 10-shot evaluation with 10 labeled examples per class. Results are repeated and averaged across the predefined 100 splits of the novel classes.
- Class distributions :
 - Base Classes:** Rolled-in_scale, Scratches, Inclusion. (Pre-training phase)
 - Novel Classes:** Pitted Surface, Crazing, Patches. (Few shot fine-tuning phase)

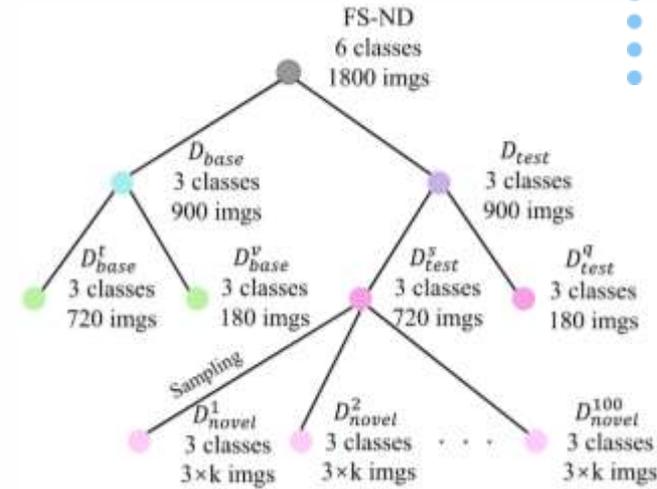


Fig. 5. Structure of k-shot FS-ND, where D_{base}^t is adopted to pre-train models in the base training stage, and D_{base}^v can be utilized to evaluate the performance of pre-trained models. Besides, $D_{novel}^1 \sim D_{novel}^{100}$ are 100 groups of support pre-examples for fine-tuning pre-trained models during the few-shot fine-tuning stage, and D_{test}^q serves as a benchmark to contrast the detection accuracy of fine-tuned models. [2]

[2] H. Wang, Z. Li, and H. Wang, "Few-Shot Steel Surface Defect Detection," *IEEE Transactions on Instrumentation and Measurement*, vol. 71, pp. 1–12, 2022

Experimental setup :

Evaluation metrics



● Mean Average Precision (mAP@0.5) :

- Area under Precision-Recall curve
- IoU threshold of 0.5 for detection
- Averaged across all defect classes

● Frames Per Second (FPS) :

- Critical for real-time industrial applications
- Hardware: RTX 4090, batch size 32, 320×320input

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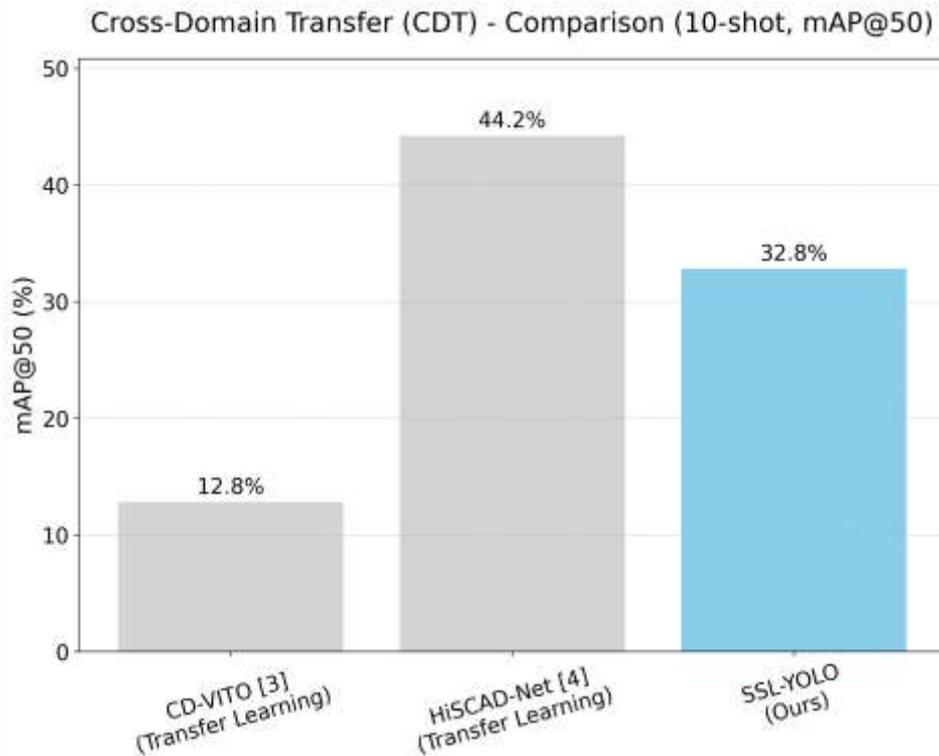
Results & Discussion



Few-shot learning benchmarking scenarios

Scenario	Scope	Pre-training Data	Fine-tuning Data
Cross-Domain Transfer (CDT)	Adapt general model	Large general datasets (e.g., COCO)	Few-shot target defects (all classes)
In-Domain <u>Self-Supervised</u> Full Fine-tuning (ISS-FFT)	Leverage abundant unlabeled domain data	Unlabeled target domain images	Few-shot labeled defects (all classes)
In-Domain <u>Self-Supervised</u> Novel Fine-tuning (ISS-NFT)	Adapt to new classes	Unlabeled base defect images	Few-shot novel classes only
In-Domain <u>Supervised</u> Novel Fine-tuning (IS-NFT)	Update model for new classes	Labeled base defect classes	Few-shot novel classes only

SSL-YOLO 10-Shot mAP@50 Results Across Different FSL Strategies



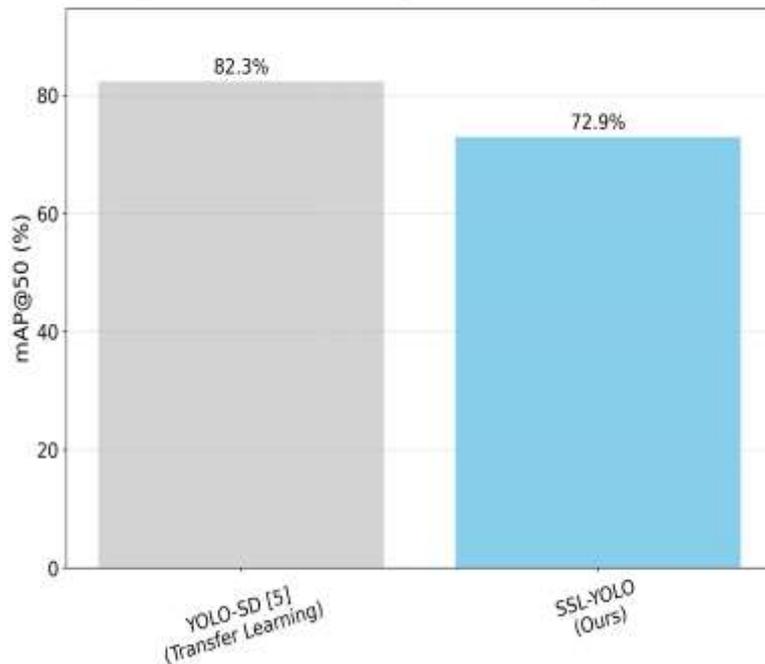
[3] Y. Fu et al., "Cross-Domain Few-Shot Object Detection via Enhanced Open-Set Object Detector," Sept. 27, 2024, arXiv: arXiv:2402.03094.

[4] S. Luo, B. Liu, H. Chen, Z. Wang, R. Yang, and Y. Huang, "Hierarchical Scale Enhancement Network with Contrast Encoding for Few-Shot Liquid Crystal Display Defect Detection," IEEE Sensors J., pp. 1–1, 2025.

SSL-YOLO 10-Shot mAP@50 Results Across Different FSL Strategies



In-Domain Self-Supervised Full Fine-tuning (ISS-FFT) - Comparison (10-shot, mAP@50)

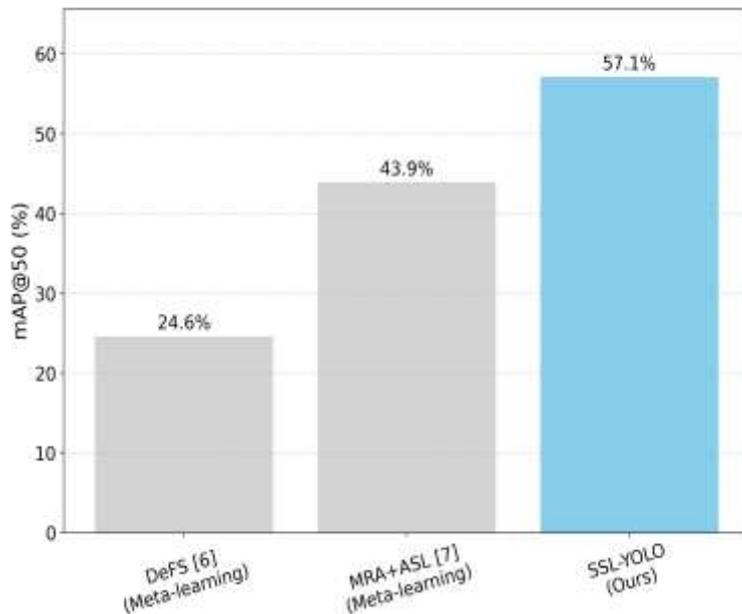


[5] Y. Wen and L. Wang, "Yolo-sd: simulated feature fusion for few-shot industrial defect detection based on YOLOv8 and stable diffusion," *Int. J. Mach. Learn. & Cyber.*, vol. 15, no. 10, pp. 4589–4601, Oct. 2024.

SSL-YOLO 10-Shot mAP@50 Results Across Different FSL Strategies



In-Domain Self-Supervised Novel Fine-tuning (ISS-NFT) - Comparison (10-shot, mAP@50)



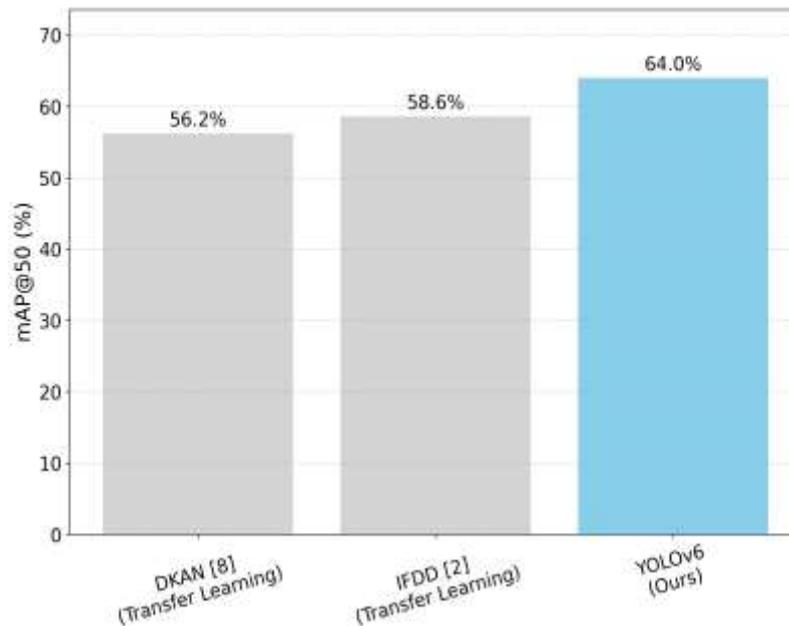
[6] X. Guo, P. Zhang, P. Zheng, Z. Zhang, and J. Liang, "A Decoupled Few-Shot Defect Detection Approach via Vector Quantization Feature Aggregation," *IEEE Transactions on Instrumentation and Measurement*, pp. 1–1, 2025.

[7] Y. Deng and Y. Song, "Few-Shot Steel Plate Surface Defect Detection with Multi-Relation Aggregation and Adaptive Support Learning," *ISIJ Int.*, vol. 63, no. 10, pp. 1727–1737, Oct. 2023.

SSL-YOLO 10-Shot mAP@50 Results Across Different FSL Strategies

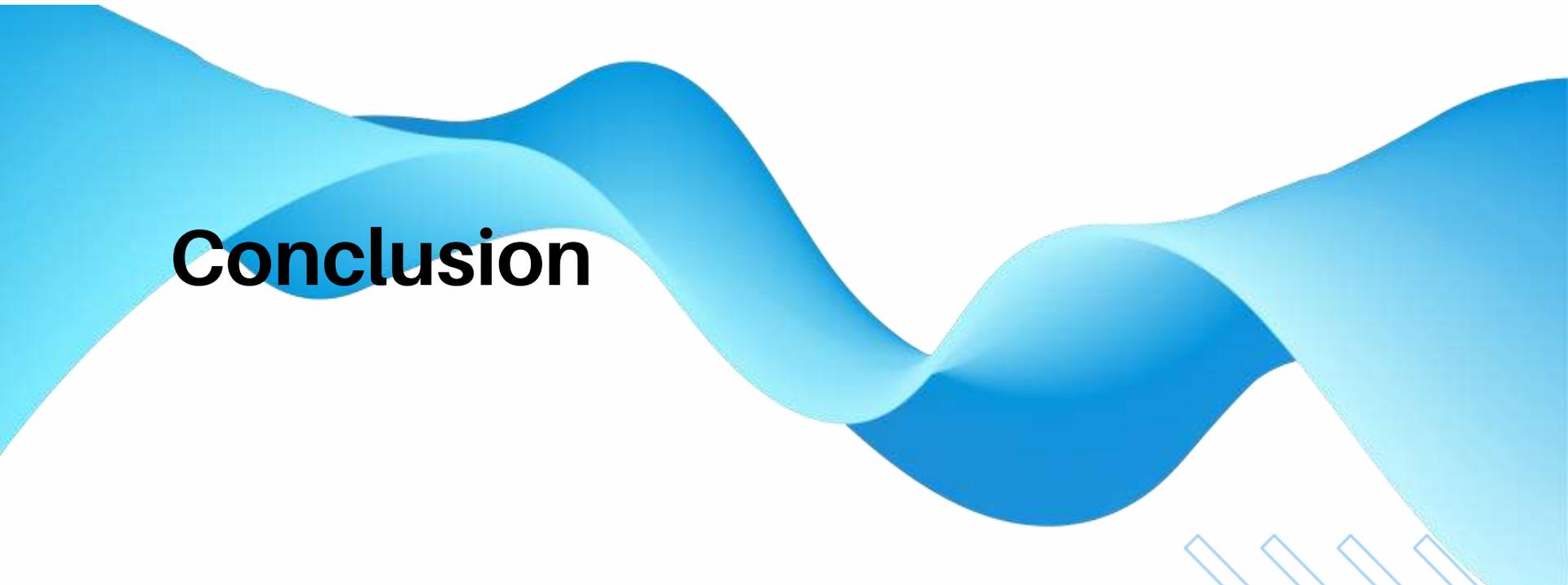


In-Domain Supervised Novel Fine-tuning (IS-NFT) - Comparison (10-shot, mAP@50)



[2] H. Wang, Z. Li, and H. Wang, "Few-Shot Steel Surface Defect Detection," IEEE Transactions on Instrumentation and Measurement, vol. 71, pp. 1–12, 2022.

[8] C. Sun, L. Gao, X. Li, and Y. Gao, "A New Knowledge Distillation Network for Incremental Few-Shot Surface Defect Detection," 2022.

A decorative background consisting of several overlapping, wavy, light blue shapes that create a sense of movement and depth. The shapes are layered, with some appearing more prominent than others, and they span across the width of the slide.

Conclusion



Conclusion



In-domain pre-training consistently outperforms cross-domain transfer for steel defect detection tasks.



SSL-YOLO effectively leverages unlabeled domain data through contrastive learning, providing a robust initialization for defect detection.



The use of a modern YOLO-family architecture provides a significant practical advantage with inference speeds reaching over 436 FPS.



Ultimately, this provides a practical and performant solution that serves as an accessible alternative to more intricate FSL methodologies, as it requires no specialized modules.



Thanks for your attention

